

1. Introduction

Component trees [1]:

- Represent the hierarchy of connected components (CCs) of the level sets of a grayscale image;
- Efficiently represented by max-trees and widely used;

Component-hypertrees [2]:

- Extension of component trees using increasing connectivities;
- Efficient ways of updating hypertrees from previous connectivities have been presented [3];
- Goal: an efficient way of representing hypertrees.

2. Proposed Method

Suppose a grayscale image f and a sequence $(\mathcal{A}_1, \dots, \mathcal{A}_n)$ of increasing sets of neighboring pixels are given. Then, the proposed algorithm follows the template below:

1. Initialize **parent** (array representing a max-tree);
2. Initialize the hypertree (empty at the beginning);
3. For $1 \leq i \leq n$:
 - (a) For (p, q) neighbors in \mathcal{A}_i :
 - i. Update **parent** by connecting p and q [4]. Track changes by marking nodes and arcs;
 - (b) Update the hypertree by allocating marked nodes and arcs.

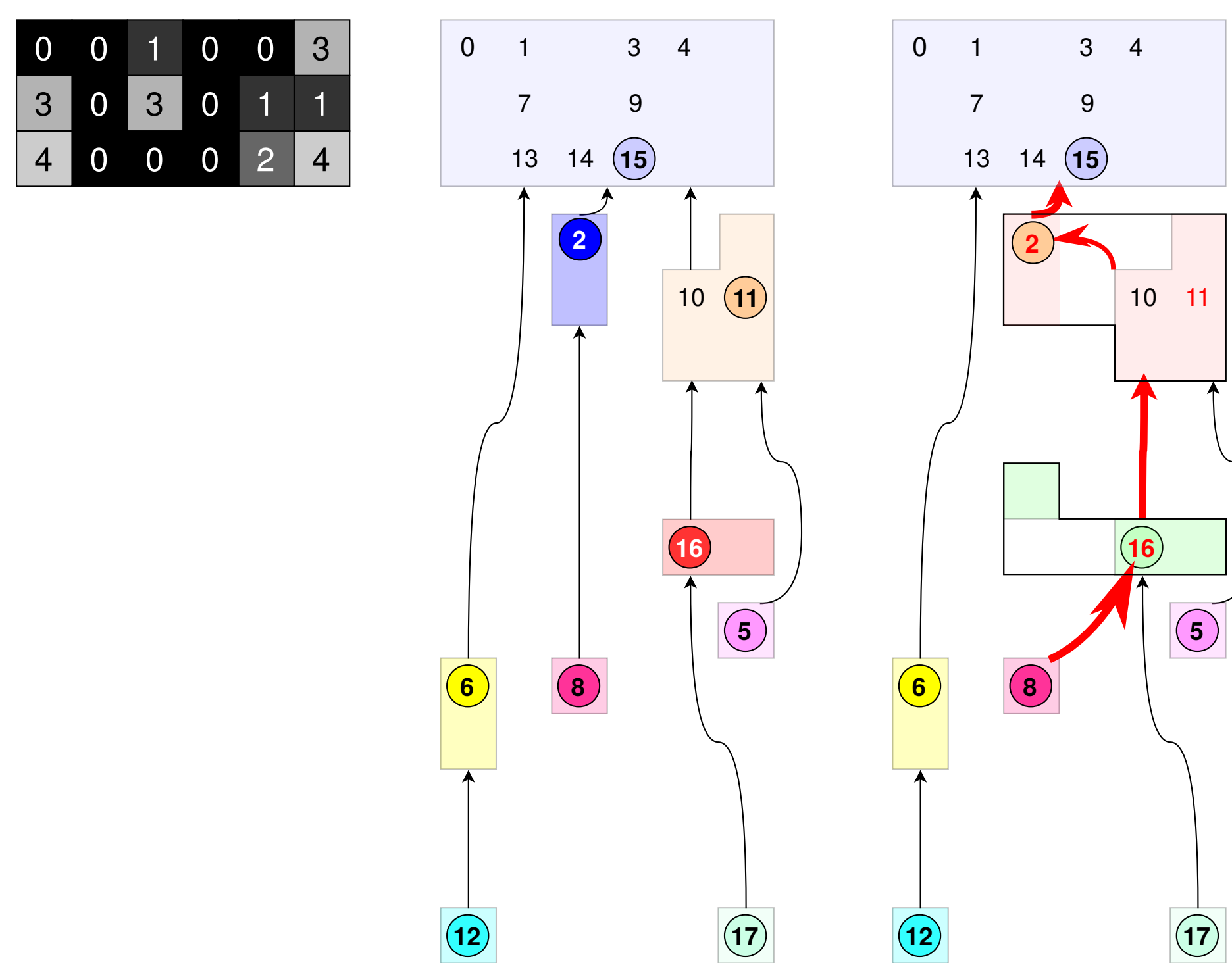


Figure 1: Left: a grayscale image; middle: its max-tree using 4-connectivity; right: updating the max-tree by connecting pixels (8, 16). Nodes and arcs in red are marked.

5. Conclusion

- An efficient way of computing and storing hypertree was presented;
- Computation of attributes in this structure will be presented in a later date.

3. Minimal Component-Hypertree

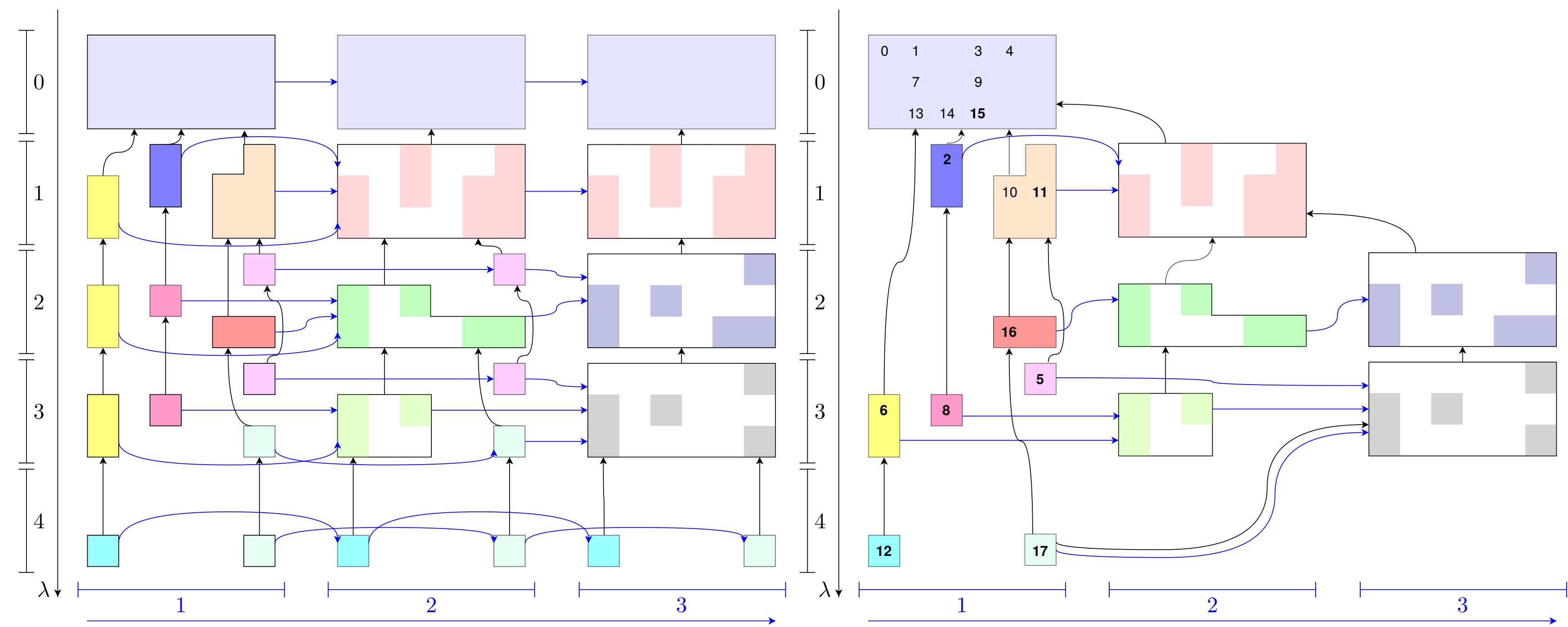


Figure 2: Left: complete hypertree; right: minimal component-hypertree. Numbers inside nodes represent stored pixels.

Minimal component-hypertree is the smallest graph satisfying:

1. No repeated nodes;
2. All inclusion relations;
3. Pixels stored only once;
4. Nodes do not depend on nodes with higher connectivity index to be reconstructed.

4. Results

Time consumption:

- Updating the max-tree is the most time consuming step;
- Only 3% to 6% of time used to allocate structures.

Number of nodes and arcs compared to other representations:

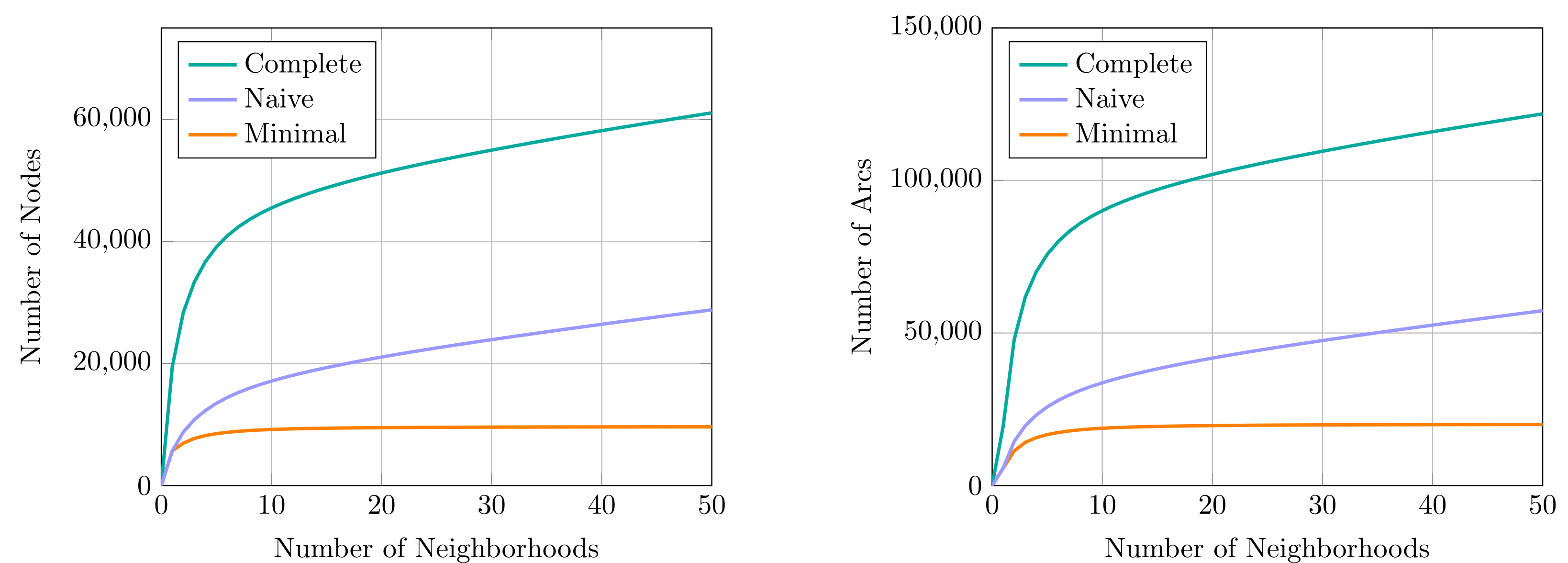


Figure 3: Comparison of number of nodes and arcs for 3 different representations of component-hypertrees. “Naive” refers to n max-trees built independently. Data was obtained from the Born Digital Dataset from the ICDAR [5].

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7. References

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